

D7 : (old title) Numerical simulation of integrated circuits for future chip generations

(new title) Index determination and structural analysis using Algorithmic Differentiation



Andreas Griewank (C. Tischendorf until 09/2006)

Dagmar Monett* (M. Selva until 09/2006)

René Lamour, Lutz Lehmann (since 09/2007)

* : maternity leave (06/2007 – 10/2007) and half time position (11/2007 – 02/2008)

DFG Research Center Matheon
Mathematics for key technologies



**DAE Example**

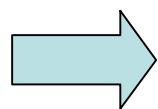
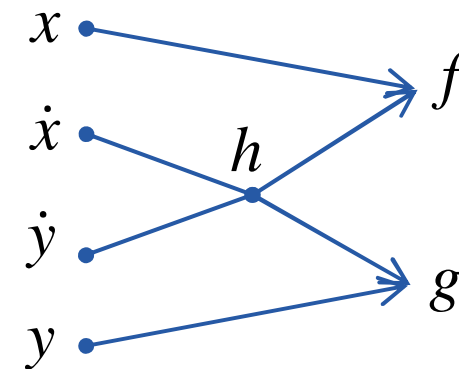
$$f(x, h(\dot{x}, \dot{y})) = 0$$

$$g(y, h(\dot{x}, \dot{y})) = 0$$

$$x, y, h, f, g \in \mathbb{R}$$

Jacobian

$$\frac{\partial(f, g)}{\partial(\dot{x}, \dot{y})} = \begin{pmatrix} \frac{\partial f}{\partial h} \\ \frac{\partial g}{\partial h} \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial h}{\partial \dot{x}} & \frac{\partial h}{\partial \dot{y}} \end{pmatrix}$$

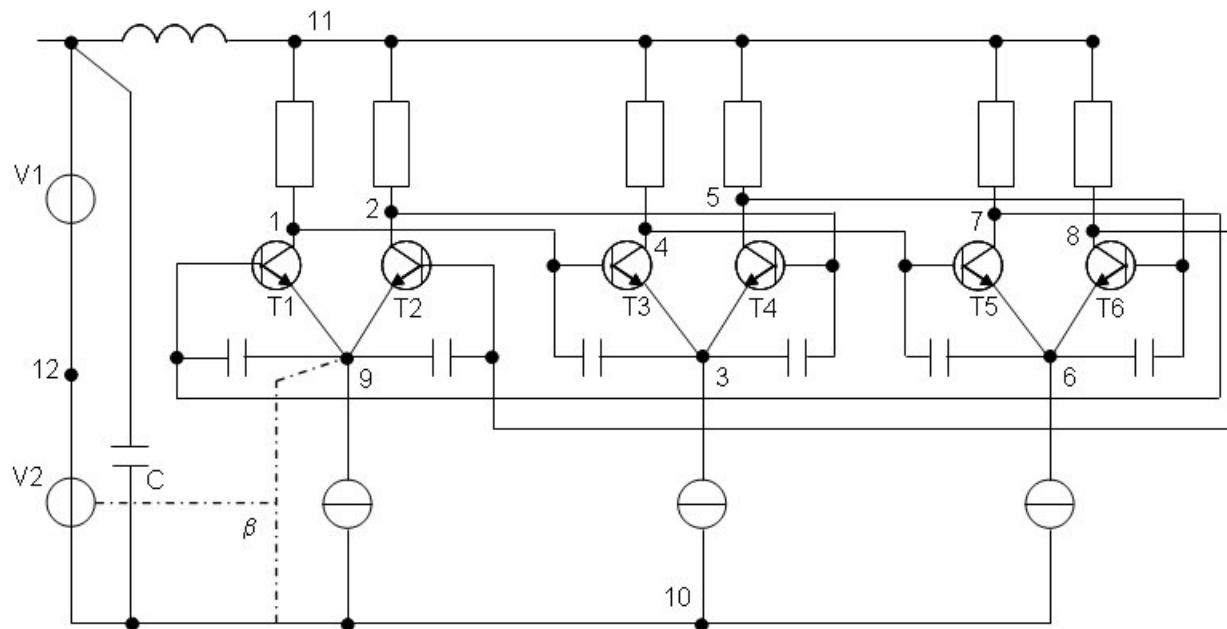
has rank ≤ 1 Corresponding
computational graph

Transformation to ODE for (\dot{x}, \dot{y}) impossible!
Structural Analysis à la Pantelides fails!!!



Some applications

- ▷ Circuit simulation (focus of original project)
- ▷ Electromechanical problems (dynamo, plate condenser)
- ▷ Multiple pendulum
- ▷ Robotic arm



Criteria for
index 3 or higher:

CV-loops

&

LI-cutsets





D7 history

- ▷ First funding period
 - ▷ Circuit-device coupled simulations
 - ▷ Determination of suitable discretizations
- ▷ Second funding period, first stage (Tischendorf)
 - ▷ Incorporation of a system integrator
 - ▷ Discretization of new semiconductor device models
 - ▷ Inclusion of 2D models by applying the Scharfetter-Gummel approach

Occurring challenges

- ▷ Determination of the **tractability index**
 - ▷ Computation of **consistent initial values**
-  treated in second stage



DAEs given by the **general equation**:

$$f((d(x(t)))', x(t)) = 0, \quad t \in I \quad \bar{z}(t) = d(\bar{x}(t))'$$

"Random" path $\bar{x}(t)$ yields linearized system with coefficients:

$$A(t) = \frac{\partial f}{\partial z}(\bar{z}(t), \bar{x}(t)), \quad B(t) = \frac{\partial f}{\partial z}(\bar{z}(t), \bar{x}(t)), \quad D(t) = \frac{\partial d}{\partial x}(\bar{x}(t))$$

Continuous matrix function sequence:

$$\begin{aligned} G_0 &:= AD, \quad B_0 := B, \\ G_{i+1} &:= G_i + B_i Q_i && \text{(if } \det(G_{i+1}) <> 0 \\ &= (G_i + W_i B_i Q_i)(I + G_i^- B_i Q_i), && \text{ return index = } i + 1 \text{)} \\ B_{i+1} &:= (B_i - G_{i+1} D^- \underline{(DP_0 \dots P_{i+1} D^-)' DP_0 \dots P_{i-1}}) P_i \end{aligned}$$

Originally: differentiation approximated by finite differences!!!



Repeated Differentiations \cong **Taylor series arithmetic + Shift op.**
on original specification!!

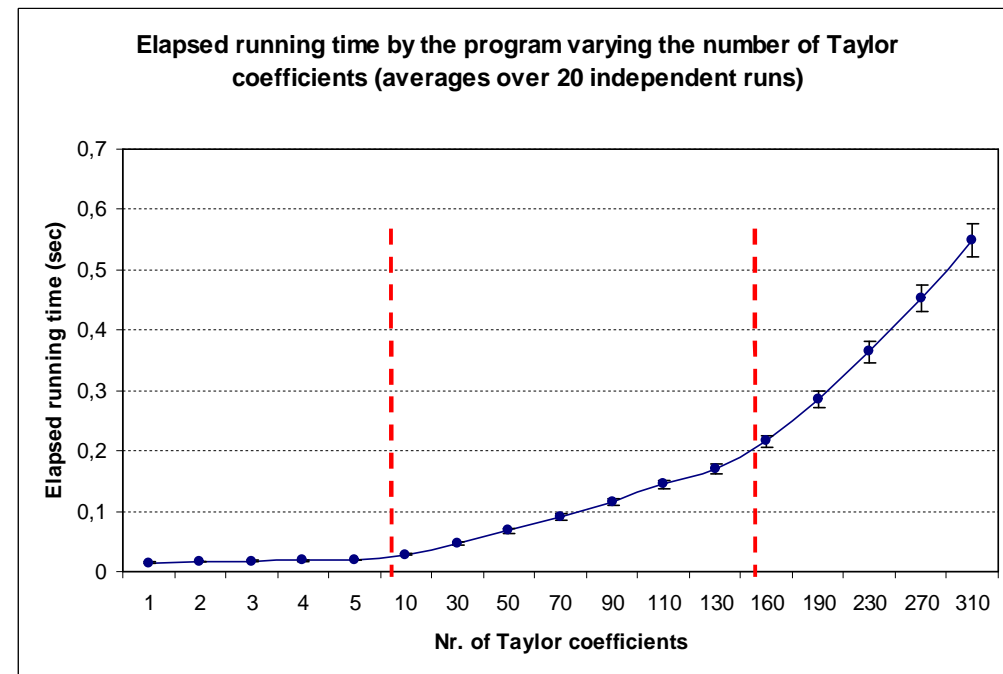
“**Algorithmic Differentiation**” yields the matrices of polynomials

$$A(t), B(t), D(t)$$

No truncation errors

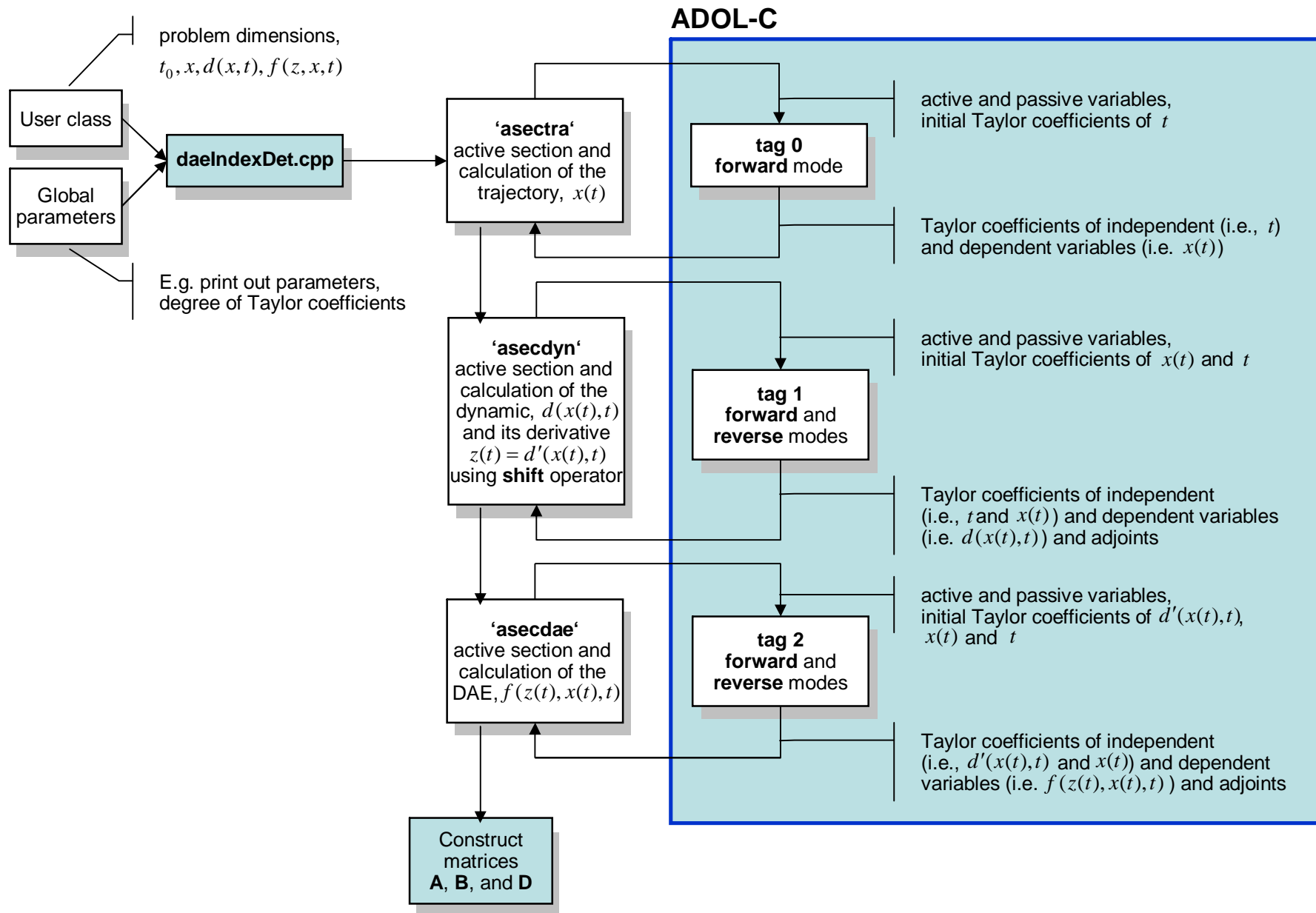
Term	$Q_{1,13}$ rel.err.
$(t - 1)^0$	0.0
$(t - 1)^1$	5.000e-16
$(t - 1)^2$	2.000e-16
$(t - 1)^3$	1.478e-15
$(t - 1)^4$	6.153e-15
Term	$Q_{2,13}$ rel.err.
$(t - 1)^0$	6.790e-14
$(t - 1)^1$	1.404e-13
$(t - 1)^2$	2.094e-13
$(t - 1)^3$	2.785e-13
$(t - 1)^4$	—

Quadratic complexity in degree





Use of Algorithmic Differentiation techniques





Example: Bike Dynamo

(In cooperation with project D13)

(Index 4)

$$\dot{p} = v$$

$$\dot{v} = \tilde{f}(v, j_L, t) - \lambda$$

$$0 = p - z(t)$$

$$C\dot{e} + Ge - j_L = 0$$

$$\dot{\phi} - e = 0$$

$$\phi = \phi_L(v, t).$$

p : position of the mass point

v : velocity

e : voltage

ϕ : magnetic flow

j_L : conductance

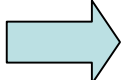
m, k, k_0, C, G are known

with

$$\tilde{f}(v, j_L, t) = \frac{f_{mech}}{m} + \frac{2\pi}{mk} k_0 j_L \sin(2\pi kvt)$$

$$f_{mech} = gm \tan(\alpha)$$

$$\phi_L(v, t) = k_0 r \cos(2\pi kvt)$$

E.g. $t = 0$  Singular point

The new method correctly computes the index even at problem singularities!!!



Main achievements

- ▶ **Exact differentiations** without explicit specification of derivatives expressions
- ▶ **High accurate** results (e.g. checking eps-conditions: equal to 0 **up to machine precision**). Accurate calculation of the index / consistent initial values (for the linear case)
- ▶ **New matrix-algebra operations** to deal with AD (e.g. implementation of special matrix-matrix multiplications, QR decomposition of **matrices of Taylor polynomials**, etc.) with **operator overloading in C++**
- ▶ **New program and library** for the index determination and the consistent initialization



Cooperations within MATHEON and externally

Cooperations within application area

D13 (higher index problems , device models for electrical circuits)

Cooperations with other application areas

C12 (software development, AD issues, algebraic equations solving)

External Cooperations

1st half (until 09/2006):

A. Jünger (Univ. Mainz)
M. Günther (Univ. Wuppertal)
R. Rianza (Univ. Madrid, Spain)
C. Führer (Univ. Lund, Sweden)

2nd half:

C. Tischendorf, M. Selva (Univ. Cologne)
F. Mazzia (Università di Bari, Italy)
J. D. Pryce (Cranfield Univ., UK)
N. S. Nedialkov (McMaster Univ., Canada)
S. Campbell (North Carolina State Univ., USA)
P. Barton (MIT, USA)
H. G. Bock (Univ. Heidelberg)
A. Walther (Univ. Dresden)



1. Computation of consistent initial values

- ▶ Nonlinear case, via [März/Lamour] (**3 months**)

2. Sparse implementation

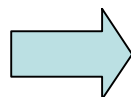
- ▶ Sparse LU-based implementation of [März/Lamour] using Taylor arithmetic (**6 months**)
- ▶ Investigate connections to approaches of [Campbell] & [Kunkel/Mehrmann]

3. Structural analysis

- ▶ Exploration of extension of [Pantelides/Pryce] to computational graphs (**3 months**)



4. If 3. promising

-  Development and implementation of method (**in additional year**)



Solution of introductory example based on graph

Expanded system

$$z - h(\dot{x}, \dot{y}) = 0$$

$$f(x, z) = 0$$

$$g(y, z) = 0$$

Maximal Degree of Variables

x	y	z
1	1	0
0	-	0
-	0	0



Solution of introductory example based on graph

Expanded system

$$z - h(\dot{x}, \dot{y}) = 0$$

$$f(x, z) = 0$$

$$g(y, z) = 0$$

Maximal Degree of Variables

x	y	z
1	1	0
0	-	0
-	0	0

Occurrence of derivatives determines structural index via **maximal transversal**

Combinatorial subtasks:

- ▶ Identification of replicated subgraphs
- ▶ Maximal Weighted Matching on DAG
- ▶ Linear Assignment Problem on Matrix



Statistics I: Publications, Talks, etc

Refereed Publications 2006-2008:	1
Submitted Preprints:	1
Books:	1
Conference Proceedings:	4
Further publications:	4
PhD Thesis (completed):	1 (first stage)
Habilitations:	–
Plenary Lectures:	–
Invited talks:	2
Offers (Prof. and similar):	–



Public funding

BMBF project

Multiskalensysteme in Mikro- und Optoelektronik: Numerische Simulation von Hochfrequenzschaltungen der Kommunikationstechnik
(until 09/2006,
C. Tischendorf and M. Selva continued the cooperation)

BMBF project

NOVOEXP (Numerische Optimierung ... für optimale Versuchsplanung ... in der Chemie ...) im Förderschwerpunkt: *Mathematik für Innovationen in Industrie und Dienstleistungen* together with Univ. Heidelberg, TU Berlin, Univ. Marburg, BASF, Knauer
Cooperation topic: AD for DAEs



External Industrial Cooperations

Infineon Technologies, Quimonda

(mainly accomplished until 09/2006, first stage)



Software

MECS: Multiphysical Electric Circuit Simulator

A Matlab-program for the simulation of electrical circuits

<http://www.mi.uni-koeln.de/~mselva/software.html>

(Initiated inside D7 and further developed at the University of Cologne)

daeIndexDet: Program for the index determination in DAEs

indexdet: Corresponding library

Using Algorithmic Differentiation techniques (**ADOL-C** package for AD)

<http://www.mathematik.hu-berlin.de/~monett/indexdet/indexdet.html>

Internal Workshop

Index computations and structural analysis of DAEs (18/02/2008)

Invited guests:

R. März (Humboldt-Univ. zu Berlin)

C. Tischendorf (Univ. zu Köln)

J. Pryce (Cranfield University, UK)